

# Outline

Goal: Noether's (1<sup>st</sup>) Thm

- What is it?
- Principle of Least Action & Lagrangian
  - ↳ Calculus of Variation
- Derive Euler Lagrange (EL) Equations
- EL  $\Rightarrow$  Newton's 2<sup>nd</sup> law
- "Physicist Proof" of Noether Thm
  - ↳ Examples



# Noether's 1<sup>st</sup> Law

Symmetry  $\Rightarrow$  Conservation Law  
 $\hookrightarrow$  energy conservation

# Classical Mechanics

Slogan: "Nature is lazy!"

Def: Action *find stationary action*

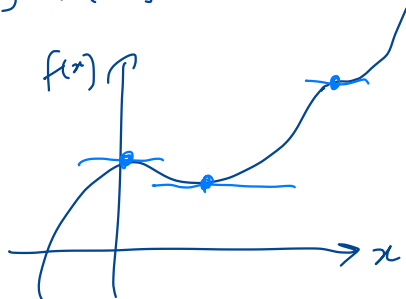
$$S = \int_{t_1}^{t_2} L(x, \dot{x}) dt$$

Lagrangian

position

velocity

1D calculus



e.g.  $L = T - V$

kinetic  $\swarrow$   
potential  $\nwarrow$

for class. mech.



side note:

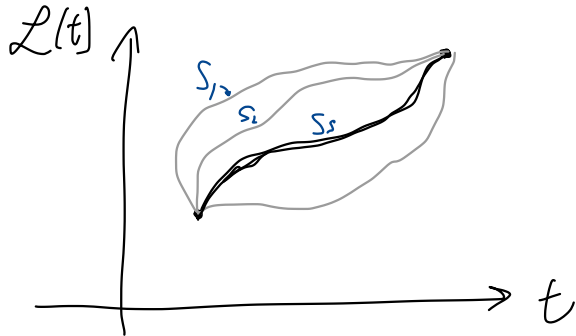
For simple harmonic oscillator,  
action is max

# Calculus of variation

$S[L]$

↑ functional

aim: vary  $L$  to find stationary pt for  $S$



$$S = \int dt \mathcal{L}(x, \dot{x})$$

$$\delta S = \int dt \left( \frac{\partial \mathcal{L}}{\partial x} \delta x + \frac{\partial \mathcal{L}}{\partial \dot{x}} \delta \dot{x} \right)$$

↑ variation

Use physics:  $\delta \dot{x} = \frac{d}{dt}(\delta x)$

$$\delta S = \int dt \left( \frac{\partial \mathcal{L}}{\partial x} \delta x + \frac{\partial \mathcal{L}}{\partial \dot{x}} \frac{d}{dt}(\delta x) \right)$$

Integration by part:  $\frac{\partial \mathcal{L}}{\partial \dot{x}} \delta x \Big|_{\text{boundary}} - \int dt \frac{d}{dt} \left( \frac{\partial \mathcal{L}}{\partial \dot{x}} \right) \delta x$

$$\delta S = \int dt \delta x \left[ \frac{\partial \mathcal{L}}{\partial x} - \frac{d}{dt} \left( \frac{\partial \mathcal{L}}{\partial \dot{x}} \right) \right]$$

= 0

EL Eq!

$$\frac{\partial \mathcal{L}}{\partial x} - \frac{d}{dt} \left( \frac{\partial \mathcal{L}}{\partial \dot{x}} \right) = 0$$

$$\frac{\partial \mathcal{L}}{\partial x} = \frac{d}{dt} \left( \frac{\partial \mathcal{L}}{\partial \dot{x}} \right)$$

NTS EL eq.  $\Rightarrow$  N2 law

$$\mathcal{L} = T - V = \frac{1}{2} m \dot{x}^2 - V(x)$$

$$F = m a !$$

$$\text{LHS} = - \frac{\partial V(x)}{\partial x} = F \quad (\text{conservative law})$$

$$\text{RHS} = \frac{d}{dt} \left( \frac{\partial}{\partial \dot{x}} \left( \frac{1}{2} m \dot{x}^2 \right) \right) = \frac{d}{dt} (m \dot{x}) = m \ddot{x} = m a$$

"Physicist Proof" of Noether Thm symmetry  $\Rightarrow$  Conservation law

$$\text{Symmetry} \Rightarrow \delta L(x, \dot{x}) = 0$$

$$\delta L(x, \dot{x}) = \frac{\partial L}{\partial x} \delta x + \frac{\partial L}{\partial \dot{x}} \delta \dot{x}$$
$$\underbrace{\qquad\qquad\qquad}_{\frac{d}{dt}(\delta x)}$$

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \delta x \right) - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \right) \delta x$$

$$\delta L = \delta x \underbrace{\left( \frac{\partial L}{\partial x} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \right) \right)}_{\text{EL eq.}} + \underbrace{\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \delta x \right)}_{\text{Conservation}}$$

# In classical field theory

scalar field  $\varphi(\vec{x})$  4 vector  $(t, x, y, z)$

Aside: index notation:  $\partial_\mu \varphi(x) = \begin{pmatrix} \frac{\partial \varphi}{\partial t} \\ -\frac{\partial \varphi}{\partial x} \\ -\frac{\partial \varphi}{\partial y} \\ -\frac{\partial \varphi}{\partial z} \end{pmatrix}$

Spacetime interval  $(t, \vec{x})$

$$\Delta s^2 = (\Delta t)^2 - (\Delta \vec{x})^2$$

$$x_\mu = \begin{pmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$g^{\mu\nu} = \begin{pmatrix} +1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix}$$

$$x_\mu x^\mu = x_\mu (g^{\mu\nu} x_\nu) = g_{00} x_0 x_0 + g_{11} x_1 x_1 + g_{22} x_2 x_2 + g_{33} x_3 x_3 = (x_0)^2 - (x_1)^2 - (x_2)^2 - (x_3)^2$$

$$\mathcal{L}(\varphi, \partial_\mu \varphi)$$

$$\delta \mathcal{L} = \underbrace{\left[ \frac{\partial \mathcal{L}}{\partial \varphi} - \partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi)} \right]}_{\text{EL for field}} \delta \varphi + \underbrace{\partial_\mu \left( \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi)} \delta \varphi \right)}_{J^\mu}$$

$$J^\mu = \begin{pmatrix} P \\ \vec{J} \end{pmatrix}$$

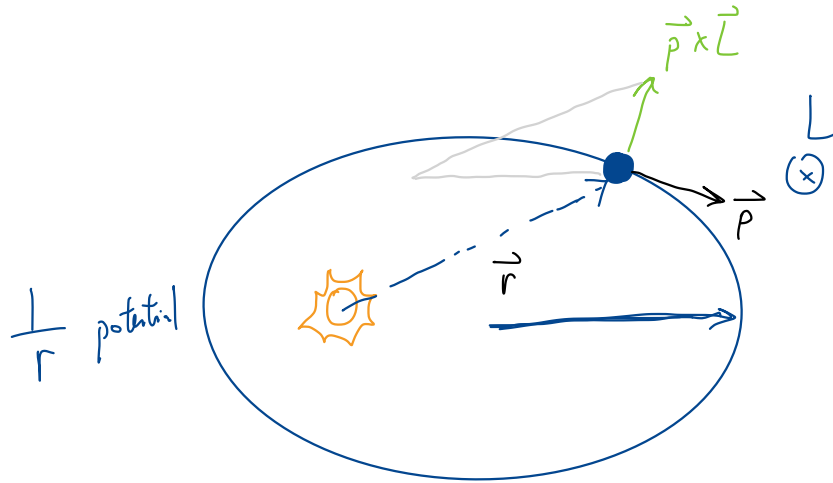
$$\partial_\mu J^\mu = 0$$

↑ electric current

charge conservation

$$\frac{\partial \rho}{\partial t} - \nabla \cdot \vec{J} = 0$$

Laplace-Runge-Lenz vector



In 4D, a free particle constrained on  $S^3$   $\curvearrowright$  3D sphere



Symmetry	Conservation
spatial translation	momentum
spatial rotation	angular momentum
time translation	energy